

JY DDA Series

General Introduction



User Manual Version:

V1.0.0

Revision Date:

August 19, 2024

Table of Contents

1.General Information	. 4
2.Order Information	. 5
3.DDA Product	. 6
3.1 Introduction	6
3.2 Pannel	6
3.2.1 Front Pannel	6
3.2.2 Rear Pannel	7
3.3 Operating DDA: DDA Mode	8
3.4 Operating DDA: EDAQ Mode	9
4.Software	10
5.Operating DDA Product	11
5.1 DDA Mode	11
5.1.1 System Setup and Configuration	11
5.1.2 Operating Target and Host Program	14
5.1.3 DDA Management	18
5.2 EDAQ Mode	22
5.2.1 System Setup (EDAQ Mode)	22
5.2.2 DDA Operating (EDAQ Mode)	22
6.About JYTEK	25
6.1 JYTEK China	25
6.2 JYTEK Software Products	25
6.3 JYTEK Warranty and Support Services	25
7.Statement	26
Figure 1 Front Pannel	6
Figure 2 Rear Pannel	7
Figure 3 RS-485 Interface	7
Figure 4 Power Supply	8
Figure 5 Operating DDA: DDA Mode	9
Figure 6 Operating DDA Step: EDAQ Mode	9
Figure 7 Install V1.5.0 or above FirmDriveRuntime	12
Figure 8 Install 1.1.0 or above JYDM	12
Figure 9 System Initial	13
Figure 10 Select DHCP Mode	14
Figure 11 Targe program development	15
Figure 12 Host Program development	15
Figure 13 Download DDA-5323 Example	15
Figure 14 Host and Target program	16
Figure 15 Target Configuration	16
Figure 16 Start Host Program	17
Figure 17 Connect Host task and Target task	17

Figure 18 Data acquisition	
Figure 19 Device management	
Figure 20 Startup Management	20
Figure 21 Start RT Target Task	20
Figure 22 Host Receive Data from RT Target	21
Figure 23 Files Storage Management	21
Figure 24 System Setup (EDAQ Mode)	
Figure 25 Download JY5320 Example	
Figure 26 Modify Alias Name in Example	
Figure 27 JY-5320 Example Winform	24
Figure 28 EDAQ Mode Display	24
Table 1 JY DDA Products	4

1. General Information

This document presents the general information of JY DDA measurement products. Table 1 lists the current available JY DDA products. The technical specifications of the DDA products are identical to those of PXIe and PCIe models. Users should follow the datasheet links to download the specifications.

Model Name	Main Function	User manual Link
DDA-5500 Series	Multi-Function DAQ	5510/5511 User Manual 5515/5516 User Manual
DDA-5320 Series	Multi-Function DAQ	5321/5322/5323/5324 Specs and Manual
DDA-9515	Dynamic Signal Analysis	9515/9516 User Manual
DDA-6311	Thermistor module	6311 User Manual
DDA-6312	Thermocouple Module	6312 User Manual

Table 1 JY DDA Products

2. Order Information

Please download JYTEK <JYPEDIA>, you can quickly inquire the product prices, ordering information and available accessories.

- DDA-9515 (PN: JY4489567-01)
 Distributed Data Acquisition Platform with built-in 8-channel, 24-bit, 256kS/s
 DSA
- DDA-6312 (PN: JY8178692-01)
 Distributed Data Acquisition Platform with built-in 16-channel, 24-bit, channelto-channel isolated thermocouple input module
- DDA-6311 (PN: JY1841190-01)
 Distributed Data Acquisition Platform with built-in 16-channel, 24-bit, channelto-channel isolated RTD temperature input module
- DDA-5321 (PN: JY649942601)
 Distributed Data Acquisition Platform with built-in 32-channel, 16-bit, 1MS/s/channel, 16 DIO, simultaneous sampling Multifunction I/O Module
- DDA-5322 (PN: JY5222640-01)
 Distributed Data Acquisition Platform with built-in 16-channel, 16-bit, 1MS/s/channel, 8 DIO, simultaneous sampling multifunction I/O module
- DDA-5323 (PN: JY2160804-01)
 Distributed Data Acquisition Platform with built-in 32-channel, 16-bit, 200 kS/s/channel, 16 DIO, simultaneous sampling multifunction I/O module
- DDA-5324 (PN: JY6200498-01)
 Distributed Data Acquisition Platform with built-in 16-channel, 16-bit, 200 kS/s/channel, 8 DIO, simultaneous sampling multifunction I/O module

3. DDA Product

3.1 Introduction

DDA stand for Distributed Data Acquisition. DDA Products are primarily developed based on the DDA System carrier board. The DDA System carrier board is a distributed data acquisition (DAQ) platform with similar capabilities to PCIe/PXIe-1010 boards, but it features a distinct interface design suitable for a variety of applications modules can be utilized for collecting sensor data distributed data acquisition and control systems, enhancing the flexibility and scalability of the systems. When paired with the existing daughter board from JYTEK, it can be assembled into various configurations of DAQ boards to meet different requirements.

All DDA products have two operating modes: **DDA mode** and **EDAQ mode**. In DDA mode, the program actually runs on the DDA System, operating independently without reliance on a PC host. All software drivers and applications execute directly on the DDA device, which features a customized Linux operating system; In EDAQ Mode, all software drivers actually running on the host PC., there is no difference between the EDAQ mode and traditional PCIe/PXIe/USB devices.

3.2 Pannel

3.2.1 Front Pannel

The front panel of the DDA is divided into two sections, one for the LED lights that indicate the operational status of the DDA and the other for the connectors.

Special Note: Connectors may vary among different models of DDAs, and the actual DDA product should be used as the reference.



Figure 1 Front Pannel

3.2.2 Rear Pannel

The rear panel of the DDA device is composed of five parts, which are the RS485 interface, RJ45 network port, USB interface, MicroSD card slot, and power supply interface. Additionally, the rear panel also includes a reset hole.



Figure 2 Rear Pannel

Note: USB-C is reserved for future use.

RS485:

The connector definition for the RS485 interface is as follows: Users can choose to connect the DDA device to the factory's internal network through the RS485 interface, leveraging the excellent anti-interference capability of RS485 to achieve DDA communication in the complex environment of the factory.



Figure 3 RS-485 Interface

RJ45:

The RJ45 interface is an 8-pin interface, through which the DDA device is connected to the Ethernet. Users can communicate with the DDA device via the TCP protocol.

USB:

The rear panel of the DDA device includes a USB 2.0 interface, which can be used for connecting external wireless network cards or other USB interface devices.

Reset:

In the event of an abnormal system condition, the DDA device can be restarted to resume normal operation using the Reset button. To initiate a reset, press and hold the Reset button with a pin for 5 to 10 seconds, which will cause the DDA device to restart and function in DHCP mode. For a reset that results in the device operating in static mode, press and hold the Reset button for more than 12 seconds. For detailed operational instructions, please refer to Section 5.1.1.

Micro SD Slot:

The Micro SD slot is used for loading SD cards and serves as the external storage for the DDA device. Consequently, the DDA device can save the lower-level machine program and the data collected by the lower-level machine onto the SD card.

Power Supply:

The DDA device supports a DC power supply of 9-36V. The power supply interface includes V+, Vcom and GND. For the interface definition, please refer to the Figure shown below.



Figure 4 Power Supply

3.3 Operating DDA: DDA Mode

When operating in DDA mode, all software drivers and applications execute directly on the DDA device, which features a customized Linux operating system. To operating DDA, user should follow the operation step which is show in the figure below, the more detailed operation of DDA is introduced in section 5.1.



Figure 5 Operating DDA: DDA Mode

3.4 Operating DDA: EDAQ Mode

When operates in EDAQ mode, all operations are similar to those of a standard PXI/PCI DAQ. The data transmission method has simply been changed from PXI/PCIe bus to network transmission. The usage and operation process in the EDAQ mode can be referred to the figure below. The more detailed operations of EDAQ Mode are introduced in section 5.2.



Figure 6 Operating DDA Step: EDAQ Mode

4. Software

The software development environment for DDA products is primarily completed on the Visual Studio platform. The program development for the lower machine (the device or system that interacts directly with the hardware) is mainly based on the **SeesharpMonoDebugger** template. Communication between the upper machine (the user interface or control system) and the lower machine is primarily accomplished by invoking the **SeeSharpTools.JY.TCP** class library for data transmission.

The development of software on the lower machine includes key steps such as setting the IP address, establishing login credentials, referencing the DDA driver, executing a five-step data collection procedure, and facilitating data uploads. Meanwhile, the upper machine's software development aims to achieve two core functions: the reception of data from the lower machine and the subsequent presentation and analysis of that data.

5. Operating DDA Product

This chapter provides the operation guides for JY DDA board, including **DDA Mode** operating guide and **EDAQ Mode** operating guide.

We provide many sample programs for this device. Please download the sample programs for this device. You can download a JYPEDIA excel file from our web www.jytek.com. Open JYPEDIA and search for DDA product in the driver sheet. In addition to the download information, JYPEDIA also has a lot of other valuable information, JYTEK highly recommend you use this file to obtain information from JYTEK.

The following operational section will **use DDA 5323 as an example** to demonstrate how to use DDA products for data acquisition.

5.1 DDA Mode

In DDA mode, the operation and management are divided into three parts, totaling eight steps. This chapter will provide a function introduction and operational demonstration for each step to help users quickly get started with the DDA product. Figure 5 Show the Diagram of DDA Mode

5.1.1 System Setup and Configuration

To use DDA products, you need to install some relevant drivers and software on the PC, including **JYDM version 1.1 or above** and **FirmDriveRuntime version 1.5 or above**. After that, you need to perform the **DDA Initialization** on the device using JYDM

Step1: FirmDriveRuntime

FirmDriveRuntime is JYTEK's hardware driver architecture. FirmDriveRuntime fully implements the PXI interface specification on FPGA, laying a solid foundation for the stability of JYTEK module hardware. FirmDriveRuntime has the inherent characteristic of cross-platform compatibility, allowing all JYTEK module hardware to operate under both Windows and Linux. JYTEK 's FirmDriveRuntime has been certified by Microsoft. User can download driver from website of JYTEK.



Figure 7 Install V1.5.0 or above FirmDriveRuntime

Step2: JYDM

JYDM is the device manager developed by JYTEK for devices under the PXI, PCI, USB, and TXI bus protocols, and is already connected to control DDA products. Users can utilize JYDM to manage chassis, controllers, and board that conform to the PXI specification. JYDM also provides updates and maintenance for JYTEK drivers and firmware and offers test programs for quick verification of the board. User can download JYDM from website of JYTEK.



Figure 8 Install 1.1.0 or above JYDM

Step3: DDA Initialization

Before using the DDA Products, it is necessary to initialize the relevant settings for the DDA device. When using DDA for the first time, you need to configure the device's username and password, and set a device alias in JYDM to facilitate subsequent device management.

Learn by example 5.1.1

- Open JYDM, and you can find the corresponding DDA device in the device loading bar on the left side. In the right-side 'Believe Information' bar, you can view detailed information about the DDA device, including the device's alias name, IP address, FPGA model, memory, and disk information.
- There are three buttons above the status bar, and the functions they possess are shown in Figure 9.

@ DDA5323 *DDA-5323* - IVDM	Change Root Password	
Refresh () About	Postart Davisa	
All Devices All Devices PXIe-2519G3 "Chassis 1" Style-3125e "Chassis 1Slot1" Style-3125e "Chassis 1Slot1" Style-313 "PXIeSlot5" Style-7131 "PXIeSlot5" Remote System DA5323 "DDA-5323"	Save ChangePassword Reboot Sytem Settings Change Alias Name Alias Name DDA-5323 Host Name DDA5323-123456789 IP Address 192.168.123.123 DNS Name DDA5323-123456789 Vendor J/TEK Model DDA5323 Operating System Linux 4.9.0-xillmx-v2017.4 Comment DDA-1010 test board Status Connected System Time 2024-04-15 16:21:55 + 08:00	ne 1
	System Resource Total Physic Memory 494 MB Available Physic Memory 366 MB Main Disk Space 14494 MB Available Disk Space 11847 MB CPU Usage 10%	

Figure 9 System Initial

Additionally, as a distributed device, the DDA hardware is deployed within the network, so it is necessary to configure the network parameters of the DDA to ensure reliable communication. IP Settings for DDA can be configured by JYDM Network Setting or pressing the Reset button on DDA device.

 Open JYDM, In the options bar below, select "Network Setting", then choose "DHCP" in the "IPv4 Config". Using a dynamic IP address can provide more flexibility in establishing connections and communication between the Host and the RT Target.

⊕My System ⊡ ₽Remote System	🗟 Sava 🔒 ChangePasseo	Set IPv4	Confia	as DHCP
DDA5323 'DDA-5323'	eth0 Settings		J	
	MAC Address	00.04.35.00.16.53		
	IPv4 Config	DHCP v		
	IPv4 Address	10.1962/14.107		
	Net Mask	255.255.255.0		
	Gateway	10.196.214.1		
	DNS Server1	10.196.214.11		
	DNS Server2	10.196.214.13		

Figure 10 Select DHCP Mode

- IP Settings of DDA can be configured via the reset button. The location of the reset button is referred to Figure 2. When the reset button is pressed for 5-10 seconds, the DDA will operate in DHCP mode; when the reset button is pressed for more than 12 seconds, the DDA will operate in static mode, with the static IP being set to 169.254.1.6. After pressing the reset button, the DDA device will restart, which will take some time, and then users can re-identify the DDA device through JYDM.
- For the DHCP mode, it is suitable for integrating the DDA into an existing network. For the static mode, it is suitable for connecting the DDA device to a local network without an internet connection (for example, by directly connecting the host computer and the DDA device with an Ethernet cable).

5.1.2 Operating Target and Host Program

DDA's Application and software development is divided into the development of **Target Program** and **Host Program**, both of which are based on Visual Studio. The program development for the lower machine (the device or system that interacts directly with the hardware) is mainly based on the **SeesharpMonoDebugger** template. Communication between the upper machine (the user interface or control system) and the lower machine is primarily accomplished by invoking the **SeeSharpTools.JY.TCP** class library for data transmission.

Step4: Target Program

The development of software on the lower machine includes key steps such as setting the IP address, establishing login credentials, referencing the DDA driver, executing data collection procedure and facilitating data uploads.

//配置参数 aiTask.Mode = (JY5320.AIMode)Enum.Parse(typeof(JY5320.AIMode), param.Mode.ToString()); aiTask.SampleClock.Source = (JY5320.AISampleClockSource)Enum.Parse(typeof(JY5320.AISampleCl
if (aiTask.SampleClock.Source == JY5320.AISampleClockSource.External) {
aiTask. SampleClock. External. Terminal = (JY5320. ClockTerminal)Enum. Parse(typeof(JY5320. C aiTask. SampleClock. External. ExpectedRate = param. SampleRate;
} else
aiTask.SampleRate = param.SampleRate;
aiTask.SamplesToAcquire = param.SamplesToAcquire;
aiTask.DisableCalibration = true;
data = new double[param.SamplesToAcquire, param.ChannelCount]; //开始任务

Figure 11 Targe program development

Step5: Host Program

The Host Program development aims to achieve two core functions: the reception of data from the lower machine and the subsequent presentation and analysis of that data.



Figure 12 Host Program development

We provided examples of both the upper-level and lower-level machine programs for DDA to facilitate users' quick start. Please Download **DDA-5323 Examples.zip** from JYPEDIA first.

简仪科技 JYTEK				
Drivers	" T	Update Date 斗	Category 🖵	Support Module 🖃
DDA6312 V1.0.0 Examples.rar		2024/7/19	Example	6312
DDA5323 V1.0.0 Examples.rar		2024/7/19	Example	5323
DDA9515 V1.0.0 Examples.rar		2024/7/19	Example	9515

Figure 13 Download DDA-5323 Example

Learn by example 5.1.2

- Connect the signal source's positive outputs to DDA-5323 AI Ch0 (AI0+, Pin #45) negative terminals to the ground (AI0-, Pin#11).
- Set a sinewave signal (f=2KHz, Vpp=10V).
- Open Analog Input-->Winform AI Continuous project. Each file contains a host project and target project. The RT Target is configured into the DDA device to perform data acquisition tasks. The Host task is to obtain the data collected by the Target through communication connections.
 - 🔺 🛋 Analog Input
 - 🔺 🛋 Al Continuous
 - ◊ C# Host-AlContinuous
 - ▷ C# Target-AlContinuous

Figure 14 Host and Target program

• Select the target task, right-click to enter the properties interface, choose RemoteHost, and enter the correct IP address, as well as the username and password. Then, start Target task.

服务	Target-AlContinuo	us*	AlContinuous.cs [设计]	Target-AlContinuous.cs			解决方案资源管理器		
191	应用程序	配置(C)· 活动(Debug)	✓ 平台(M): 活动(Δm)	CPID V			o o 🟠 🛗 - 🏼 o -	5 C @ @ 🗲 🗕	
	生成	homes, have buy	T LIGHT - HIGH (191						م
1200	生成事件			3. Configure Cor	rrect		🖬 解决方案'DDA5320.E	xamples' (35 个项目)	
8	调试	Remote Host Settings	II	Username and P	assword		Analog Input		
100	資源			, osername and r	ussitiona		Al Continuous	ntinuous	
	設分	Host 192.168.214.166	The hi	ostname of the machine that will ru	In your code	生成(1)	e 💭 Tarrash AlC	inntinuous	
l i	この数据					重新生成(E)			
	然名	Username root	Ine us	ername with which to login to the	host	清理(N)		Continuous.cs	
	安全性					分析(Z)		nalog Trigger wousAnalogTrigger	
	发布	Password ****	The p	assword to authenticate with the ho	ost 🛞	发布(B)		luousvilulogingger	
	代码分析					限定为此范围(S)		ationada a la aTria a se a	
	RemoteHost*				di di	新建解决方案资源管理器	见图(N)	s	
		2. Calcut David shall and				生成依赖项(B)		tinuousAnalogTrigger	
		2. Select RemoteHost				添加(D)			
1					Ĥ	管理 NuGet 程序包(N)		ContinuousAnalogTrigger.	
l i					\$	设为启动项目(A)		igital Trigger	
l i						调试(G)			
						对交互窗口进行项目初始	Ł	泉賞埋器	
l i						源代码管理(S)			- ų ×
					*	剪切(T)	Ctrl+X	,任	
l i					6	粘贴(P)	Ctrl+V		
l i						移陈(V)	Del	Target-AlContinuo	us.csproj
l i				1.Right Click Tar	get 🕒	重即名(M)			
1				Select Propert	ies 📃 🔍	加坡坝田(L)	*****		
1				· · · · · ·		住又件谈說官理講中打开;	(件夹(X)		
	输出					属性(R)	Alt+Enter		

Figure 15 Target Configuration

• Launch the Host program, and when both identify the online status, the output will display 'wait host connect'.

AlContinuous.cs # Host-AlContinuous.cs [Btt] # 4 X Target-AlContinuous.cs	 解決力変統新普理論 - ?
Image: All and Control of the state of t	Al Confinence Al Conf
#문양평5: 年代 · 『 등] 등 등 결 (知 · 『 등] 등 등 결 (知 · 『 등] 등 등 결 (知 · 『 등] 등 등 결 (知 · · · · · · · · · · · · · · · · · ·	- # - X

Figure 16 Start Host Program

• Click the button to connect to the RT Target task. After a successful connection, it will display 'wait for commands'. Then click the button to start data acquisition.

d DDA5320 参 /YDDA5323键现法完成样(Host)	- 0 ×	▼1 ₽ 快速協力 👂 - 6
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0 2.5 5 min 5 min 3.6 2.10 1.17 1.17 Click 1.17 1.17 1.17 1.17 1.17 1.17 0 0.00 1.00 1.00 1.00 1.17 0 0.00 0.00 0.00 1.00 1.00 0 1.00 0.00 0.00 0.00 1.00 1.00	レル他は	Control
[1] 21 (1) (1) (1) (1) (1) (1) (1) (1) (1) (1	Debug/SeeSharpTools, JY, TCF, AL ¹⁴ + H	- ま × 品質物類が汗 200 文符-





Figure 18 Data acquisition

5.1.3 DDA Management

As a distributed device, users can manage all DDA devices through JYDM. Users can perform **Device Management**, **Startup Management** and **External Storage management** via JYDM.

Step6: Device Management

The host computer can identify all DDA devices within the same network segment through JYDM. These devices will be displayed in the Remote System bar on the left side of the interface, and users can click on the corresponding device to perform more operation settings.



Figure 19 Device management

Step7: Startup Management

Users can set the DDA Target startup program through JYDM. After the startup program settings are completed, user can start lower-level machine program through JYDM, and Host Computer can read the collected data from the DDA through the upper-level machine program which including TCP connection.

Learn by Example 5.1.3-1

 Select "Application Management" in the options bar below, choose the exe application that the lower machine needs to run, and then use the class library SeeSharpTools.JY.TCP on the Host to establish a connection and communicate with the RT Target, receiving the data collected by the RT Target.

3 문 My System 승 문 All Devices 승대 PXIe-2519G3 "Chassis	s1*	🗟 Save 🤞 Chang	pePassword C Reboot	/		Sta	rtup P	rogram
- 1: PXIe-3125e "Chu	ssis1Slot1*	Startup Applic	ation List	/		IV	lanaye	ment
		Start Priority 10	Path JYTEK/Apps/WedDemo/D	Argument 192.168.123.130	Enabled	Status P Not Started	Start	
				Ref	resh [d	t Delete		
		Remote File To			/	-	F	ile
		Name			line .	Made	Mana	gement
		⇔ <mark>₹</mark> Apps ∲- <mark>₹</mark> Wed	Demo			2024-04-	11 16:43:29 29 16:52:03	
		ि हूँ, Apps के-हूँ, Wed Refresh	Demo Delete Unzi	p Create Sub	• Folder	2024-04 2024-03- Upload File	11 19-43-29 29 16-52-03 Set as Startup	
🖗 Edit Startup Ap	oplication	De R Apps De R Wed Rafresh P System @ Net	Denno Delete Units twock Settings (22 Application	p Create Sub	Folder	2024-0F 2024-03- Upload File urage Managem	29 16:52:03 Set as Startup ent	
🖗 Edit Startup Ag	oplication	Effective System	Denno Deline Unio Involk Settings: III: Applicatio	o Mangement	Folder	2024-0F 2024-0F	set as Startup Set as Startup	tion
Edit Startup App Path	JYTEK/Apps/	P System @ Net	Denno Deline Usa Involk Settings III: Applicate	p Craste Sul	Folder	Upload File	se stantup figura	tion
Edit Startup Ap Startup App Path Start Argument	oplication JYTEK/Apps/	Editech F System Made TextApp. exe	Denne Deline Usa Invork Settings III: Applicate	e Costa Sul	External St	2024-05- 2024-03- Upload File crage Managem	sta Sano Startup figura	tion
Edit Startup Ap Startup App Path Start Argument Start Friority	JYTEK/Appz/	EstApp. exe	Denne Deinte Unst Invok Settings (22 Applicate	p Create Sub	External St	2024-05- 2024-03- Uplead File orage Managem	st as Santup Startup	tion

Figure 20 Startup Management

- Connect the signal source's positive outputs to DDA-5323 AI Ch1 (AI1+, Pin #47) negative terminals to the ground (AI1-, Pin#13).
- Set a sinewave signal (f=2KHz, Vpp=6V).
- Clicking the "Start" button to the right of the startup item program can initiate the data acquisition program on the RT Target. If you wish to terminate the program, you can click the "Kill" button.

My System Remote System	Save 🔒 ChangePassword 🕐 Reboot
DDA5323 "DDA-5323"	Startup Application List
	Start Priority Path Argument Enabled Status PID
	10 JYTEK/Apps/demo1/Target V Running 1579 Kill 10 JYTEK/Apps/demo1/Target V Running 1579 Kill
	JYTEK Device Manager X
	j Start Success.
	Refresh Edit Delete
	确定
	Remote File Tree
	Name Size Modified
	Apps 2024-04-23 15:40:17
	₩ ₩edDemo 2024-03-29 16:52:03
	Refresh Delete Unzip Create Sub Folder Upload File Set as Startup

Figure 21 Start RT Target Task

• After starting the RT Target program in JYDM, we can read the data collected by the RT Target through the Host's TCP communication program.

R A W Report of 1041 Beauty of		
emo · · · · · · · · · · · · · · · · · · ·	amo.Form1 · @_button_start_Click(object ser	nder, EventArgs e) • Ø 🕞 🔍 🖏
<pre>public partial class Form : Form (</pre>	💀 Form1	
<pre>private void putrom_trart_Click(object sender, Bount // HEIOYO/DBW data = new double(SIDO): // UBW client: Romote 0 = trans;</pre>		2010
 private void timerTick(bijset sender, Sventkrgs e) timeri_Enabled = faise; if (clien.kwilabidomples >= data_length = 3) // JENT_TORK_enderStream(ref data); client.ResdBataStream(ref data); 		Start Step
<pre>// Ergend easyChartH.Plot(data); } timerL.Enabled = true; }</pre>	671 639 1006 1174 1341	

Figure 22 Host Receive Data from RT Target

Step8: External Storage management

The DDA module features an SD card slot designed for file and program storage. Utilizing JYDM version 1.1 or later, users can efficiently configure and manage these files and programs. Capabilities within JYDM include managing DDA module-related system files by creating folders, uploading programs to the lower machine, and deleting folders. The DDA module is also capable of handling external file storage and manage, including the uploading and downloading of files.

Learn by example 5.1.3-2

While the RT Target program is running for data acquisition, the collected data will be synchronized and stored in a CSV file. This file will be saved on the SD card located inside the DDA module. We can **select "External Storage Management "** in the options for the DDA product on JYDM, where the files containing the saved data are stored. By right-clicking on the corresponding file, we can either download it to the PC or delete it from the SD card.

🕻 Refresh 🕜 About					
	Save ChangePassword C Reboot				
	System Volume Information	544	2024-04-12 09:34:36		
-, 17: PXIe-7811 "PXIeSlot7"	- 20240412_072112.csv	529	2024-04-12 15:21:40		
₩ Remote System DDA5323 "DDA-5323"	Delete Download		2024-04-06-13:56-22		

Figure 23 Files Storage Management

5.2 EDAQ Mode

In EDAQ mode, the operation and management are divided into 2 parts. This chapter will provide a function introduction and operational demonstration for each part to help users quickly get started with the DDA product. Figure 6 Show the Operation Diagram of EDAQ Mode

5.2.1 System Setup (EDAQ Mode)

The Driver and Software is same as DDA Mode which including Driver FirmDriverRuntime and Software JYDM, user can get more details from Section 5.1.1

It is important to note that when using the EDAQ mode, each device must be individually assigned an alias in JYDM.

em Settings Alias Name	DDADev0
Host Name	DDA5323-F002C15035
P Address	10.196.214.166
/endor	JYTEK
Hardware Version	R3.0
Firmware Version	0.0.0
Operating System	Linux 4.9.0-xilinx-v2017.4

Figure 24 System Setup (EDAQ Mode)

5.2.2 DDA Operating (EDAQ Mode)

The use of DDA under EDAQ is completely consistent with the use of ordinary PXI/PCI bus DAQ. Specific parameters and instructions can be referred to in the manual of the same model. It is particularly important to note that when using the same model DAQ example, device aliases should be used for the selection of DDA devices.

In EDAQ mode, user can directly use the standard examples of the module. Download **JY5320 Examples.zip** from JYPEDIA.

简仪科技 JYTEK		
Drivers 🗔	Update Date 💷	Category 🖵
<u>JY5320 V1.1.3 Win.tar</u>	2024/7/19	Driver
JY5320 V1.1.2 Linux.tar	2024/4/26	Driver
JY5320 V1.1.2 Examples.rar	2024/4/26	Example
JY5320 V1.0.8 C++Examples.rar	2024/3/8	Example
JY5320 V1.0.1 Python.rar	2023/8/4	Driver
JY5320 V1.0.1 PythonExamples.rar	2023/8/4	Example

Figure 25 Download JY5320 Example

Learn by example 5.2.2

- Connect the signal source's positive outputs to DDA-5323 AI Ch1 (AI1+, Pin #47) negative terminals to the ground (AI1-, Pin#13).
- Set a sinewave signal (f=2KHz, Vpp=10V).
- Open Analog Input-->Winform Al Continuous project, modify the initialization task part of the code to start the board using an alias name of DDA product, set the following numbers as shown.



PCIe/PXIe/USB-5320 Series Single Channel Continuous Data Acquisition									-	×				
		PCIe,	'PXIe/	USB-53	20 Se	ries S	Single	Channe	el Con	tinuou	s Data Acquis	ition		
3.5-	,					.,		.,		.,	- Series1	Basic Param Configur	ation	
												Card ID	5323	\sim
з —												Slot Number	0	\sim
												Channel ID	0	\sim
2.5-												Clock Source	Internal	~
												External Clock	PFIO	\sim
2												Sample Rate(Sa/s)	200,000	*
												Samples To Acquire	100,000	*
1.5-												Input Range	$\pm 10 \text{V}$	~
1												Available Samples		
0.5	10	0 21	10 31	0 41	10 E	500	600 7	00 -	800	900 10	00	Start		

Figure 26 Modify Alias Name in Example



Figure 27 JY-5320 Example Winform

Figure 28 EDAQ Mode Display

6. About JYTEK

6.1 JYTEK China

Founded in June, 2016, JYTEK China is a leading Chinese test & measurement company, providing complete software and hardware products for the test and measurement industry. The company has evolved from re-branding and reselling PXI(e) and DAQ products to a fully-fledged product company. The company offers complete lines of PXI, DAQ, USB products. More importantly, JYTEK has been promoting open-sourced based ecosystem and offers complete software products. Presently, JYTEK is focused on the Chinese market. Our Shanghai headquarters and production service center have regular stocks to ensure timely supply; we also have R&D centers in Xi'an and Chongqing. We also have highly trained direct technical sales representatives in Shanghai, Beijing, Tianjin, Xi'an, Chengdu, Nanjing, Wuhan, Guangdong, Haerbin, and Changchun. We also have many patners who provide system level support in various cities.

6.2 JYTEK Software Products

JYTEK has developed a complete software platform, SeeSharp Platform, for the test and measurement applications. We leverage the open sources communities to provide the software tools. Our platform software is also open sourced and is free, thus lowering the cost of tests for our customers. We are the only domestic vendor to offer complete commercial software and hardware tools.

6.3 JYTEK Warranty and Support Services

With our complete software and hardware products, JYTEK is able to provide technical and sales services to wide range of applications and customers. In most cases, our products are backed by a 1-year warranty. For technical consultation, pre-sale and after-sales support, please contact JYTEK of your country.

7. Statement

The hardware and software products described in this manual are provided by JYTEK China, or JYTEK in short.

This manual provides the product review, quick start, some driver interface explanation for DDA Series family of multi-function data acquisition and modular instruments boards. The manual is copyrighted by JYTEK.

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While we try to keep this manual up to date, there are factors beyond our control that may affect the accuracy of the manual. Please check the latest manual and product information from our website.

Shanghai Jianyi Technology Co., Ltd.

Address: Room 201, Building 3, NO.300 Fangchun Road, Shanghai.

Post Code: 201203

Tel: 021-5047 5899

Website: www.jytek.com